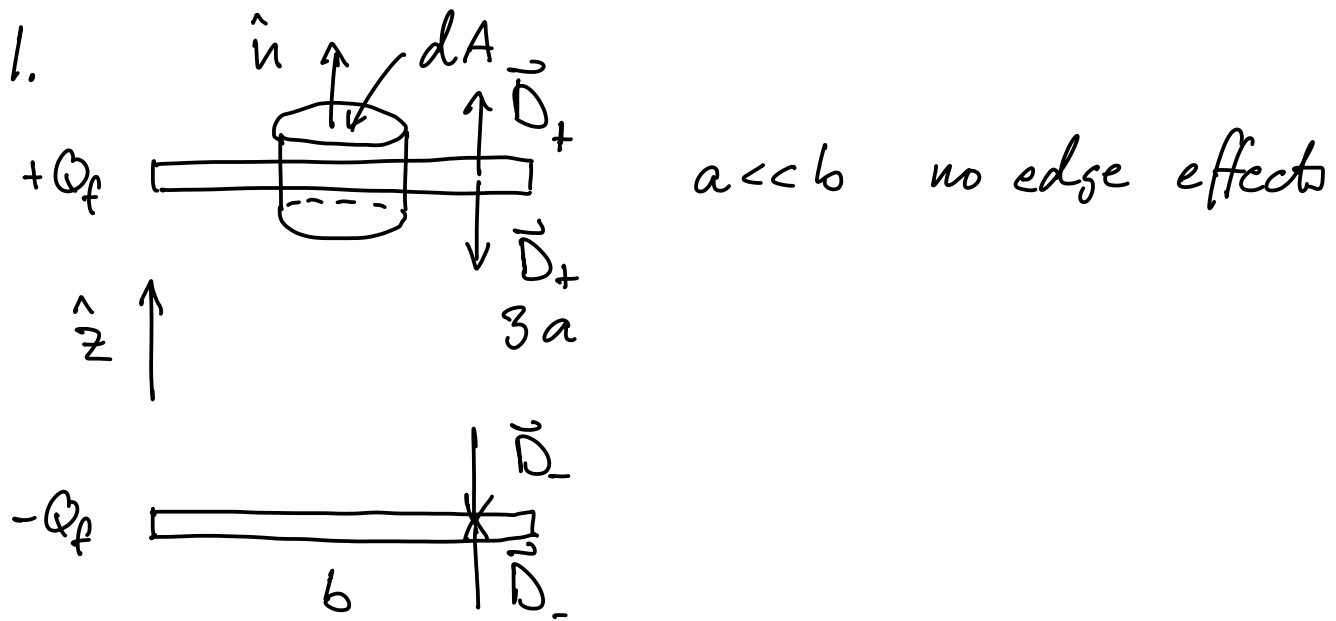


Electromagnetism exam June 3, 2016

Sketches for solutions



a) Gauss law on upper plate

$$\int \vec{D}_+ \cdot d\vec{A} = Q_{f,enc}$$

symmetry gives $\vec{D}_+ = D_+ \hat{z}$ above and $\vec{D}_+ = -D_+ \hat{z}$ below the plate

surface charge $\sigma_f = \frac{Q_f}{b^2}$

$$\Rightarrow 2D_+ dA = \frac{Q_f}{b^2} dA, \quad D_+ = \frac{\sigma_f}{2}$$

For the lower plate we get in the same way that $D_- = \sigma_f/2$

Adding the two solutions we find

$$\vec{D} = \begin{cases} -\sigma_f \hat{z} & \text{between the plates} \\ 0 & \text{outside the plates} \end{cases}$$

b, by definition we know that $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$
 for a linear medium $\vec{P} = \chi_e \epsilon_0 \vec{E}$

$$\Rightarrow \vec{D} = \epsilon_0 \vec{E} + \vec{P} = \epsilon_0 (1 + \chi_e) \vec{E} = \epsilon_0 \epsilon_r \vec{E}$$

For the upper slab we get: $\vec{E} = \frac{1}{2\epsilon_0} \vec{D}$, $\vec{P} = \frac{1}{2} \vec{D}$

and for the lower one: $\vec{E} = \frac{1}{3\epsilon_0} \vec{D}$, $\vec{P} = \frac{2}{3} \vec{D}$

c, the bound surface charge is given by $\sigma_b = \hat{n} \cdot \vec{P}$

① $\sigma_b = \hat{z} \cdot \left(-\frac{1}{2} \nabla_f \hat{z}\right) = -\frac{1}{2} \nabla_f$, $\sigma = \frac{1}{2} \nabla_f$

② $\sigma_b = -\hat{z} \cdot \left(-\frac{1}{2} \nabla_f \hat{z}\right) = \frac{1}{2} \nabla_f$, $\sigma = \frac{1}{2} \nabla_f$

③ $\sigma_b = \hat{z} \cdot \left(-\frac{2}{3} \nabla_f \hat{z}\right) = -\frac{2}{3} \nabla_f$, $\sigma = -\frac{2}{3} \nabla_f$

④ $\sigma_b = -\hat{z} \cdot \left(-\frac{2}{3} \nabla_f \hat{z}\right) = \frac{2}{3} \nabla_f$, $\sigma = -\frac{1}{3} \nabla_f$

the discontinuity in the \vec{E} -field is given by

$$(\vec{E}_{\text{above}} - \vec{E}_{\text{below}}) \cdot \hat{z} = \frac{1}{\epsilon_0} \sigma = \frac{1}{\epsilon_0} (\nabla_f + \sigma_b)$$

starting from the upper plate we have

① $0 - \left(-\frac{1}{2\epsilon_0} \nabla_f\right) = \frac{1}{2\epsilon_0} \nabla_f$ ok

② $-\frac{1}{2\epsilon_0} \nabla_f - \left(-\frac{1}{\epsilon_0} \nabla_f\right) = \frac{1}{2\epsilon_0} \nabla_f$ ok

③ $-\frac{1}{\epsilon_0} \nabla_f - \left(-\frac{1}{3\epsilon_0} \nabla_f\right) = -\frac{2}{3\epsilon_0} \nabla_f$ ok

④ $-\frac{1}{3\epsilon_0} \nabla_f - 0 = -\frac{1}{3\epsilon_0} \nabla_f$ ok

2. Potential known on spherical shell

$$V(r=R, \theta, \varphi) = k \cos \theta$$

a) no charges $\Rightarrow \nabla^2 V = 0$ except on shell

Spherical symmetry \Rightarrow we can write general solution as

$$V(r, \theta) = \sum_l (A_l r^l + B_l \frac{1}{r^{l+1}}) P_l(\cos \theta)$$

coefficients A_l, B_l fixed by bound. cond.

inside: V regular at $r=0 \Rightarrow B_l = 0$

$P_1(\cos \theta) = \cos \theta$, P_l orthogonal when integrating between $\cos \theta = -1$ and $\cos \theta = 1$

\Rightarrow only $A_1 \neq 0$

Bound. cond $\Rightarrow A_1 R \cos \theta = k \cos \theta \Rightarrow A_1 = \frac{k}{R}$

$$\Rightarrow V_{in} = \frac{k}{R} r \cos \theta$$

outside: V vanishes at infinity $\Rightarrow A_l = 0$

$P_1(\cos \theta) = \cos \theta \Rightarrow$ only $B_1 \neq 0$

Bound cond $\Rightarrow B_1 \frac{1}{R^2} \cos \theta = k \cos \theta \Rightarrow B_1 = k R^2$

$$\Rightarrow V_{out} = k R^2 \frac{1}{r^2} \cos \theta$$

b) By definition $\vec{E} = -\vec{\nabla} V$ so

$$\vec{E}_{in} = -\hat{r} \frac{k}{R} \cos \theta + \hat{\theta} \frac{k}{R} \sin \theta$$

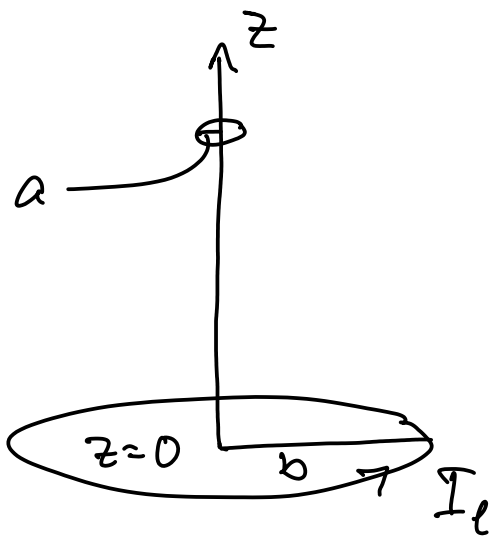
$$\vec{E}_{out} = + \hat{r} \frac{2kR^2}{r^3} \cos\theta + \hat{\theta} \frac{kR^2}{r^3} \sin\theta$$

c) Boundary conditions

$$(\vec{E}_{out} - \vec{E}_{in})|_{r=R} \cdot \hat{r} = \frac{1}{\epsilon_0} \sigma$$

$$\Rightarrow \sigma = \epsilon_0 3 \frac{k}{R} \cos\theta$$

3.



$$a \ll b$$

a) Biot-Savart:
$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^3\vec{r}'$$

Cylindrical coord: $\vec{r} = z \hat{z}$, $\vec{r}' = b \hat{s}$, $|\vec{r} - \vec{r}'| = \sqrt{z^2 + b^2}$
 $(\hat{x} \cos\varphi + \hat{y} \sin\varphi)$

The current: $\vec{J}(\vec{r}') = I_0 \hat{\varphi} \delta(r-b) \delta(z)$
 $(-\hat{x} \sin\varphi + \hat{y} \cos\varphi)$

Cross product:

$$\vec{J}(\vec{r}') \times (\vec{r} - \vec{r}') = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ -\sin\varphi & \cos\varphi & 0 \\ -b \cos\varphi & -b \sin\varphi & z \end{vmatrix} =$$

$$= \hat{x} z \cos\varphi + \hat{y} z \sin\varphi + \hat{z} \underbrace{(b \sin^2\varphi + b \cos^2\varphi)}_b$$

The field on the z-axis is then given by

$$\vec{B}(\vec{r}) = \frac{\mu_0 I_e}{4\pi} \int \frac{(\hat{x} z \cos\varphi + \hat{y} z \sin\varphi + \hat{z} b)}{(b^2 + z^2)^{3/2}} b d\varphi$$

$$= \frac{\mu_0 I_e}{2} \frac{b^2}{(b^2 + z^2)^{3/2}} \hat{z}$$

b) Faraday's law, $\vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} \vec{B}$

on integral form $\oint \vec{E} \cdot d\vec{l} = \int -\frac{\partial}{\partial t} \vec{B} \cdot d\vec{S}$

$a \ll b \Rightarrow \vec{B}$ and $\frac{\partial}{\partial t} \vec{B}$ const over small loop

$$\Rightarrow \int -\frac{\partial}{\partial t} \vec{B} \cdot d\vec{S} = \pi a^2 \left(-\frac{\mu_0 I_e}{2} \frac{b^2}{(b^2 + z^2)^{3/2}} \right)$$

$\frac{\partial}{\partial t} \vec{B} = C \hat{z}$ with $C > 0$ and the right-hand

rule $\Rightarrow \vec{E} = -E \hat{\varphi}$

so $\int \vec{E} \cdot d\vec{l} = -2\pi a E$ and

$$\vec{E} = -\frac{\mu_0 I_e}{4} \frac{ab^2}{(b^2 + z^2)^{3/2}} \hat{\varphi}$$

Ohm's law then gives $\vec{J}_s = \sigma \vec{E}$

The current goes in the $-\hat{\varphi}$ -direction, which is in agreement with Lenz law.

4. Point like dipole $\vec{p} = \tilde{p}_0 e^{-i\omega t} \hat{z}$ at $\vec{r}' = 0$.

Retarded solution

$$\vec{A}^M = \frac{\mu_0}{4\pi} \int \frac{\vec{J}^M(\vec{r}', t - \frac{|\vec{r} - \vec{r}'|}{c})}{|\vec{r} - \vec{r}'|} d^3\vec{r}'$$

The three-vector part is then given by

$$\begin{aligned} \vec{A}_{\text{rad}} &= \frac{\mu_0}{4\pi r} \int \vec{J}^M(\vec{r}', t - \frac{|\vec{r} - \vec{r}'|}{c}) d^3 r' = [\text{use hint}] = \\ &= \frac{\mu_0}{4\pi r} \frac{\partial}{\partial t} \vec{p}(t - \frac{r}{c}) = -i\omega \frac{\mu_0}{4\pi r} \vec{p}_0 e^{-i\omega(t - \frac{r}{c})} \hat{z} \\ \left[\frac{\omega}{c} = k \right] &= -i\omega \frac{\mu_0}{4\pi r} e^{i(kr - \omega t)} \vec{p}_0 \hat{z} \end{aligned}$$

b) by definition $\vec{B} = \vec{\nabla} \times \vec{A}$

in the radiation zone $kr \gg 1$ and

$$\vec{\nabla} \times \left(\frac{e^{i(kr - \omega t)}}{r} \hat{z} \right) = i \vec{k} \times \hat{z} \frac{e^{i(kr - \omega t)}}{r}$$

$$\Rightarrow \vec{B} = \frac{\mu_0}{4\pi} \frac{\omega k}{r} e^{i(kr - \omega t)} \vec{p}_0 \underbrace{\hat{r} \times \hat{z}}_{-\hat{\phi} \sin \theta}$$

Ampere's law without sources and with harmonic time dependence

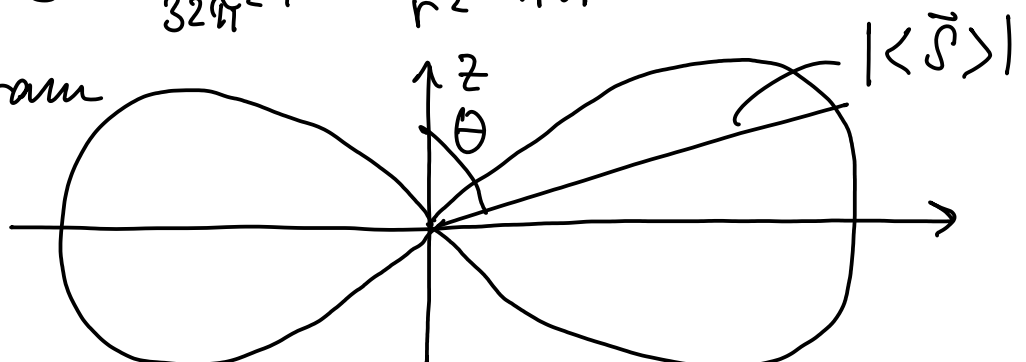
$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial}{\partial t} \vec{E} = \frac{1}{c^2} (-i\omega) \vec{E}$$

$$\Rightarrow \vec{E} = -\frac{c^2}{\omega} \frac{\mu_0}{4\pi} \frac{\omega k^2}{r} e^{i(kr - \omega t)} \vec{p}_0 \underbrace{\hat{r} \times (\hat{r} \times \hat{z})}_{\hat{\theta} \sin \theta}$$

c) Poynting vector

$$\langle \vec{S} \rangle = \frac{1}{2\mu_0} \vec{E} \times \vec{B}^* = \frac{1}{32\pi^2} \mu_0 c^2 \frac{\omega k^3}{r^2} |\vec{p}_0|^2 \sin^2 \theta \hat{r}$$

Antenna diagram



5. a) Maxwell's equations

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} \rho$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial}{\partial t} \vec{B} = 0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{B} - \mu_0 \epsilon_0 \frac{\partial}{\partial t} \vec{E} = \mu_0 \vec{J}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{B} = \vec{\nabla} \times \vec{A}$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{A}) = 0 \Rightarrow \vec{\nabla} \times \left(\vec{E} + \frac{\partial}{\partial t} \vec{A} \right) = 0$$

$$\Rightarrow \vec{E} + \frac{\partial}{\partial t} \vec{A} = -\vec{\nabla} V, \quad \vec{E} = -\vec{\nabla} V - \frac{\partial}{\partial t} \vec{A}$$

b) Magnetic field, $\vec{B} = \begin{cases} B \hat{z}, & s < s_0 \\ 0, & s > s_0 \end{cases}$

$$\vec{E} = 0, \quad V = 0 \Rightarrow \frac{\partial}{\partial t} \vec{A} = 0$$

Carl in cylindrical coordinates

$$\vec{\nabla} \times \vec{a} = \hat{s} \left[\frac{1}{s} \frac{\partial}{\partial \varphi} a_z - \frac{\partial}{\partial z} a_\varphi \right] + \hat{\varphi} \left[\frac{\partial}{\partial z} a_s - \frac{\partial}{\partial s} a_z \right] + \hat{z} \left[\frac{\partial}{\partial s} (s a_\varphi) - \frac{\partial}{\partial \varphi} a_s \right]$$

$$= 0 \qquad = 0 \qquad \begin{cases} B, & s < s_0 \\ 0, & s > s_0 \end{cases}$$

Solution: $A_\varphi = \begin{cases} \frac{Bs}{2}, & s < s_0 \\ \frac{Bs_0^2}{2s}, & s > s_0 \end{cases}$

c) The phase-shift becomes

$$\Delta\varphi = \pm \frac{q}{h} \oint \vec{A} \cdot d\vec{l} = \pm \frac{q}{h} \frac{Bs_0^2}{2} \underbrace{\int \frac{\hat{\varphi}}{s} \cdot \hat{\varphi} s d\varphi}_{2\pi}$$

or alternatively

$$\Delta\varphi = \pm \frac{q}{h} \oint \vec{A} \cdot d\vec{l} = \pm \frac{q}{h} \int (\vec{\nabla} \times \vec{A}) \cdot d\vec{S} =$$

$$= \pm \frac{q}{h} \int \vec{B} \cdot d\vec{S} = \pm \frac{q}{h} \pi s_0^2 B$$